

THE UNIVERSITY of TEXAS

HEALTH SCIENCE CENTER AT HOUSTON SCHOOL of HEALTH INFORMATION SCIENCES

Molecular Dynamics Simulation: Practice II

For students of HI 6327 "Biomolecular Modeling"

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http://biomachina.org/courses/modeling/05.html

Where Does Force Field Come From?

Fitted parameters:

- ideal values (bonds, bond angles etc)
- \bullet energy constants
- non–bonded parameters (vdW, charges)

Data for the fit:

- *ab initio* quantum mechanical energies for small molecules
- *ab initio* quantum mechanical energies from distorted small molecules
- X–ray structures of small molecules
- spectroscopic data (IR, NMR) for frequencies
- transfer free energies for vdW and charges

The X-PLOR Energy Function

 $E_{EMPIRICAL} = \sum_{p=1}^{N} [w_{BOND}^{p} E_{BOND} + w_{ANGL}^{p} E_{ANGL} + w_{DIHE}^{p} E_{DIHE} + w_{IMPR}^{p} E_{IMPR} + w_{VDW}^{p} E_{VDW} + w_{ELEC}^{p} E_{ELEC} + w_{PVDW}^{p} E_{PVDW} + w_{PELE}^{p} E_{PELE} + w_{HBON}^{p} E_{HBON}].$ (2)

Bond Stretching Energy

$$E_{BOND} = \sum_{bonds} k_b (r - r_0)^2 \tag{3}$$

- r actual bond length
- k_b energy constant
- r_0 equilibrium distance

Definition in

• Topology file: explicitly with atom names

bond CB HA

• Parameter file: with atom types, k_b , r_0

bond HA CT 1000 1.09

the sequence of atom types does not matter

Angle Bending Energy

Sum of two terms:

$$E_{ANGL} = \sum_{angles} (k_{\theta}(\theta - \theta_0)^2 + k_{ub}(r_{13} - r_{ub})^2)$$
(4)

- First term is standard angle energy.
 - $-\theta$ actual value of the angle
 - $-\theta_0$ equilibrium angle
 - $-k_{\theta}$ energy constants
- Second term is Urey-Bradley energy. Usually, this term is 0.
 - $-r_{13}$ actual 1–3 distance
 - r_{ub} equilibrium 1–3 distance
 - $-k_{ub}$ energy constant (default $k_{ub} = 0$)

Angle Bending Energy

- Topology file:
 - explicit definition:
 - angle hb1 cb hb2
 - automatic definition:

autogenerate angles true end

at the beginning of topology file note: autogenerate does not work in "patches"

- Parameter file:
 - with atom types, k_{θ} , θ_0 [ub k_{ub} , r_{ub}]

angle HA CT HA 500.0 109.0 [ub]

Dihedral Angle Energy

$$E_{DIHE} = \sum_{dihedrals} \sum_{i=1,m} k_{\phi_i} (1 + \cos(n\phi_i + \delta_i))$$
(5)

- ϕ_i actual torsion angle
- k_{ϕ_i} energy constant
- n_i periodicity
- m_i multiplicity
- δ_i phase shift

multiplicity: define several terms for same angle (e.g. $n_i = 2, 3$ for sugar puckers)

for $n_i = 0$, different functional form:

$$E_{DIHE} = \sum_{dihedrals} \sum_{i=1,m} k_{\phi_i} (\phi_i - \delta_i)^2 \tag{6}$$

- ϕ_i actual torsion angle
- δ_i equilibrium angle

Dihedral Angle Energy

Definition in

- Topology file:
 - explicit definition:
 - dihedral ca cb cg cd
 - automatic definition:

autogenerate dihedrals true end

at the beginning of topology file note: autogenerate does not work in "patches" note: *all* dihedral angles are generated

• Parameter file:

- dihedral CT CT CT CT 1.0 3 0.0 $\,$

Multiplicities have to be specified in parameter and topologies

Improper Torsion Energy

$$E_{IMPR} = \sum_{impropers} \sum_{i=1,m} k_{\phi_i} (1 + \cos(n\phi_i + \delta_i))$$
(7)

- ϕ_i actual improper torsion angle
- k_{ϕ_i} energy constant
- n_i periodicity
- m_i multiplicity
- δ_i phase shift

multiplicity: define several terms for same angle (e.g. $n_i = 2, 3$ for sugar puckers)

for $n_i = 0$, different functional form:

$$E_{IMPR} = \sum_{impropers} \sum_{i=1,m} k_{\phi_i} (\phi_i - \delta_i)^2 \tag{8}$$

- ϕ_i actual improper torsion angle
- δ_i equilibrium angle

Improper Torsion Energy

Definition in

- Topology file:
 - only explicit definition:
 - improper ca n c cb
- Parameter file:
 - improper CA N C CT 500.0 0 35.26439

Differences between dihedrals and improper torsions:

- Identical functional form
- For both, atoms need not be covalently linked
- Usually, $n_i = 0$ for impropers
 - define chirality
 - define planarity
- Often, impropers do not follow covalent bonds
- Usually, dihedrals around rotatable bonds

Van der Waals Function

Lennard–Jones potential

$$f_{VDW}(R) = \frac{A}{R^{12}} - \frac{B}{R^6}$$
(9)

$$f_{VDW}(R) = 4\varepsilon \left(\left(\frac{\sigma}{R}\right)^{12} - \left(\frac{\sigma}{R}\right)^6\right) \tag{10}$$

- $\bullet~A,B$ Lennard–Jones parameters
- $\bullet~R$ actual distance between two atoms
- $\bullet~\varepsilon$ well–depth
- $\sigma \propto$ sum of vdW radii
- $E_{min} = -\varepsilon$
- $R_{min} = \sqrt[6]{2}\sigma$
- $\bullet \ A = 4 \sigma^{12} \varepsilon$
- $B = 4\sigma^6 \varepsilon$

Van der Waals Function

Definition in

- Topology file:
 - through atom types

atom CB type=CT charge=-0.30 end

- Parameter file:
 - PARAmeter NONBond statement defines ε_i and σ_i for each atom type

nonbonded CT 0.12 3.74 0.12 3.74

2nd ε_i, σ_i pair are for 1–4 interactions

 $- \, \varepsilon$ and σ between types i and j are calculated as

$$* \varepsilon = \sqrt{\varepsilon_i \varepsilon_j} * \sigma = \frac{\sigma_i + \sigma_j}{2}$$

- PARAmeter NBFIx statement defines A,B parameters between different types

nbfix CT N 10 1000 10 1000

2nd A, B pair are for 1–4 interactions

Electrostatic Function

Coulomb law

$$f_{ELEC}(R) = Q_i Q_j \frac{C}{\varepsilon_o R} \tag{11}$$

Coulomb law w. "distance dependent dielectric"

$$f_{ELEC}(R) = Q_i Q_j \frac{C}{\varepsilon_o R^2} \tag{12}$$

- Q_i atomic charge
- $\bullet~R$ distance between two atoms
- ε_o dielectric constant e.g. for vacuum $\varepsilon_o = 1$, for water $\varepsilon_o = 80$

Electrostatic Function

Definition in

- Topology file:
 - through atomic charges

atom CB type=CT charge=-0.30 end

• PARAmeter NBONds statement:

 $-\varepsilon_o$

parameter nbonds epsilon=1 end end
- straight coulomb law ("constant dielectric"):
 parameter nbonds CDIE end end
- distance dependent dielectric:
 parameter nbonds RDIE SWITCH end end

1-4 Interactions

Some force fields have special 1–4 non–bonded parameters

• electrostatic:

param nbonds e14fac 0.4 end end

• vdW: second pair of ε, σ or A, B parameters in parameter file

nonbonded	СТ		0.1	.2	3.74	0.1	2	3.74
nbfix	СТ	Ν	10	10	000	10	10	00

 \bullet set

param nbond NBXMOD 5 end end

Long-Range Switching/Shifting/Truncation

Non–bonded energies have infinite range. Coulomb potential is modified by

• Truncation: $\Theta(R - R_{cut})$ (Step function)

parameter nbonds TRUNcation CTNB 8.5 end end

 R_{cut} is non–bonded list cutoff

• Shift entire function such that f = 0 at finite R: $(1 - \frac{R^2}{R_{off}^2})^2$

param nbonds SHIFt CTOFNB 7.5 end end note: not with RDIE

• Switch interaction gently off between R_{on} and R_{off}

```
param nbonds
SWITch CTONNB 5.5 CTOFNB 9.5
end end
```

note: not with CDIE

vdW energy is truncated or switched (with VSWItch)

Soft Repulsive Non-Bonded Energy

$$C_{rep}(max(0, (k^{rep}R_{min})^{irexp} - R^{irexp}))^{rexp}$$
(13)

- no electrostatics
- no singularity at 0
- R_{min} is defined from Lennard–Jones potential
- $k^{rep} < 1$ since potential is harder than L–J around R_{min}
- switched on by specifying $k^{rep} > 0$

```
param nbonds repel= 0.8 end end
```

Non-Bonded Lists

Time–saving device:

- calculate non–bonded energy only within R_{cut}
- determine atom pairs within R_{cut} and store on list
 param nbond CUTNB 10.5 {A} end end
 update frequency is determined by TOLErance

param nbond toler 0.5 {A} end end note: CUTNB - CTOFNB > 2 TOLE

Summary of Non-Bonded Options

```
parameters nbonds

CDIEL EPS=1.0 E14FAC=0.4

SHIFT VSWITCH CTOFNB=7.5 CTONNB=6.5

CUTNB=8.5 ATOM NBXMOD=5 TOLE=0.5

WMIN=1.5

end end
```

- NBXMOD for setup of non–bonded list:
 - NBXMOD=1 no self interactions
 - NBXMOD=2 + no 1–2 ia (bonds)
 - NBXMOD=3 + no 1–3 ia (bond angles)
 - NBXMOD=4 + no 1–4 ia
 - NBXMOD=5 like 3, but with special 1–4 parameters
- ATOM for atom-based cutoff (GROUP for groupbased cutoff)
- WMIN non-bonded warning distance (no effect on energy)

Switch energy terms on or off:

The FLAGS statement

FLAGs EXCLude ELEC END FLAGs INCLude HBON END

note: only BOND ANGL DIHE IMPR VDW ELEC switched on by default all experimental terms and HBON PELE PVDW have to be turned on explicitly

Restrict Interactions:

Range of standard interactions are modified with CONStraints INTEraction

```
constraints
  interaction (segid A) (segid A)
  interaction (segid B) (segid B)
end
```

switches off all interactions between segids

Weighting Interactions:

Weights on specific interactions are modified with CONStraints INTEraction WEIGht

```
constraints
interaction (all) (not name SG)
weights * 1 end
interaction (name SG) (name SG)
weights * 0 bonds 0.01 vdw 1 elec 1 end
end
```

reduces bond energy for disulfide bridges

note: all desired interactions have to explicitly defined

Weighting Interactions:

with PARAmeter statement

parameter bonds (name SG) (name SG) 0.0 TOKEN end

reduces the energy constant of disulfide bridges to 0, but leaves bond length alone ("TOKEN")

note: this is an example of atom based parameter definition (which will be discussed later)

Modify Charges:

Charges can be modified with VECTOR statement

```
vector do (charge = 0)
  (resn lys or resn arg or resn asp or resn glu)
```

sets all charges for some residues to 0.

Examples of X-PLOR Force Fields

PARAM19:

- standard CHARMM force field
- extended atom (no explicit aliphatic hydrogens)
- typical values for energy constants

bond	С	С	450.0	1.38
bond	CH1E	CH3E	225.0	1.52

angl CH1E CH2E CH3E 45.0 113.0

dihe	CH1E	С	Ν	CH1E	10.0	2	180.0
dihe	Х	CH1E	CH2E	Х	1.6	3	0.0

impr CH1E X X CH2E 55.0 0 35.26439

nonb C 0.1200 3.7418 0.1000 3.3854

Examples of X-PLOR force fields

Typical CHARMM force fields we use:

param19.pro / toph19.pro / toph19.pep (united atom model, only polar hydrogens)

parallh22x.pro / topallh22x.pro / toph22.pep (all hydrogen, newer force field)

Download these from class web site!

There are newer versions available (v. 27, not covered here)

The X-PLOR Scripting Language

- variables (symbols)
- \bullet if—statements
- \bullet loops
- atom selection
- data structure manipulations
- many application statements
- mathematical functions for variable and data structure manipulations

Symbol Definitions and 'EVALuate'

- \bullet recognized by $\$ sign
- \bullet symbols are defined and manipulated by EVAL uate

```
evaluate ($count = 0)
evaluate ($filename = "dg.pdb")
```

- \bullet Symbols can be
 - real numbers
 - strings
- \bullet the type definition is implicit by usage
- \bullet type conversion by encode and decode

```
evaluate ($name = encode($count))
evaluate ($number = decode($name))
```

• \$? produces list of all defined symbols

Arithmetic Operations

• Standard operations

+ - * / ** ^ () evaluate(\$number = (5*\$count)^(3+\$count))

• mathematical functions

cos sin ran ...
evaluate(\$number = sin(\$count*ran()))

Special Symbols

- Fundamental constants
 - \$pi \$kboltz
- Results of certain operations (incomplete list)
 - PRINt statements define \$result

print angle
evaluate (\$rms_angle = \$result)

- VECTor SHOW statements define \$result

vector show average (x) (all)
evaluate (\$x_ave = \$result)

ENERgy, MINImiz and DYNAmics define energy terms

energy end display \$ener \$bond \$angl

IF Statements

- basic structures:
 - IF (condition) THEN commands END IF
 - IF (condition) THEN commands
 ELSE commands END IF
 - "case" statement
 IF (condition) THEN commands
 ELSEIF (condition) THEN commands

END IF

 \bullet can be nested

...

• note: ELSEIF is not ELSE IF

IF Statements

```
- two "end if" necessary
  if ( $count eq 1 )
  then
     coor copy end
  else
     if ($count eq 2)
     then
        coor fit end
     end if
  end if
- one "end if" necessary
  if ( $count eq 1 )
  then
     coor copy end
  elseif ($count eq 2)
  then
     coor fit end
  end if
```

Loops

```
WHILE loop:
WHILE (condition) LOOP loop-name
commands
END LOOP loop-name
evaluate ($count = 1)
while ($count le 10) loop main
evaluate ($count = $count + 1)
end loop main
```

```
• FOR loop:
FOR variable IN (set)
```

```
for $filename in ( "sa_1.pdb" "sa_3.pdb" )
loop main
    coor @@$filename
end loop main
```

```
• FOR loop:
FOR variable IN ID (selection)
```

```
for $loopid in id (all) loop main
    vector show element (x) (id $loopid)
end loop main
```

Atom Selection

- select atoms for certain operations
- selection by atom name
- wildcards and ranges
- selection by atom property
- \bullet different "queries" can be connected by AND / OR
- "queries" can be negated by NOT
- parantheses necessary for combinations of AND, OR, NOT

Selection by Atom Name

- The atom name consists of
 - SEGId, segment name defined by SEGMent
 - RESId, residue "number" (also 48b etc!)
 - RESName, residue name (ALA, VAL...)
 - NAME, atom name (N, CA...)

coor select (resid 5 and name hn) ... end coor select ((resid 5 or resid 7) and name hn) .. coor select (resid 5:7 and not name h*) ... end

- Atoms can also be selected by
 - CHEM (atom type defined in topology)
 - ID (internal number)

Wildcards and Ranges

- wildcards and ranges can be used for
 - SEGId
 - $-\operatorname{RESId}$
 - RESName
 - NAME
 - CHEM
- ranges are lexigraphical order
- \bullet indicated by ":"

coor sele (name ha:hg#) ... end selects ha, hb1, hb2, hg1, hg2

 \bullet wildcard hierarchy

- "*" any string (abcd, 78, 8u)
- "#" any number (2, 43, 39987)
- "%" any character (a, 6, j)
- "+" any digit (0, 1, ... 9)
Selection by Atom Property

• ATTRibute selects on any atom property (coordinates, derivatives, mass, charge, ...)

coor sele (attribute charge > 0) ... end

• AROUnd, SAROund select atoms within cutoff of specified atoms

coor sele ((resid 1 and name ca) around 5.0) ... end SAROund selects atoms also in symmetry mates

• POINt ... CUT selects atoms around point

coor sele (point (3.0 4.0 5.0) cut 5.0) ... end

Atom Selection

BYREsidue

• BYREsidue (selection) selects all atoms in a residue

coor sele= (byres(point $(0 \ 0 \ 0) \ cut \ 5.0)$)

STOREi and RECALLi

• Atom selections can be stored and used later

vector iden (store1) (name ca)

```
coor sele= (store1) ...
coor sele= (recall1) ...
```

'VECTor' Statement

The VECTor statement allows analysis and manipulation of atom properties and names.

- VECTor SHOW ELEMent (AtomArray) (selection) lists elements and defines \$result
- VECTor SHOW AVERage (AtomArray) (selection) VECTor SHOW RMS (AtomArray) (selection) VECTor SHOW SUM (AtomArray) (selection) VECTor SHOW NORM (AtomArray) (selection)

```
vector show element (resid)
(name ca and (resid 5 and name ca) around 5.0)
```

vector show average (x) (name ca)

• VECTor DO (expression) (selection)

vector do (b = b + $x^2 + y^2 + z^2$) (all)

• VECTor IDEN (STOREi) (selection) defines a STORE to be used in atom selection later

3D Vectors and Matrices

• 3D vectors can be defined explicitly, or through atom selections

```
coor translate vector= (1 0 0) end
coor translate
    vector= (head=(resid 1 and name cb)
        tail=(resid 1 and name ca))
    distance= 5.0
```

• 3x3 matrices can be defined by

```
coor rotate
  center= (0 0 0)
  matrix= AXIS (head=(resid 1 and name cb)
       tail=(resid 1 and name ca))
  90.0
```

- or by Euler angles, Lattman angles, Quaternions, Spherical angles
- or explicitly

```
coor rotate
center= (0 0 0)
matrix= (1 0 0) (0 1 0) (0 0 1)
```

Output Files

- DISPLAY files for DISPlay statements open with SET DISPlay filename END
- PRINT files for info from PRINt statements (e.g. PRINt AN-GLes) open with SET PRINt filename END
- coordinate, structure, parameter files with WRITE COOR (structure...) OUTPut= filename end
- \bullet trajectory files

Script Example I: RMS Difference

```
set display rmsd.disp end
evaluate (maxcount = 10)
evaluate ($count = 1)
for $filename in ( @@file.list ) loop fit
  coor @@$filename
   if ($count eq 1) then
      coor copy end
  end if
  coor sele (name ca) fit end
   coor sele (name ca) rms end
  display structure $count $filename rms difference $result A
   if ($count ge $maxcount) then
      exit loop fit
   end if
   evaluate ($count = $count + 1)
end loop fit
```

Script Example I: RMS Difference

file.list contains a list of files, for example ordered by energy

"sa_1.pdb" "sa_6.pdb" ... "sa_67.pdb"

The display file rmsd.disp will look like this

structure 1 sa_1.pdb rms difference 0 A
structure 2 sa_6.pdb rms difference 1.245 A
...
structure 10 sa_67.pdb rms difference 1.87 A

Script Example II: B-Factors

```
set display rmsfluc.disp end
```

for \$loopid in id (name ca) loop rms

```
vector show element (resid) (id $loopid)
evaluate ($resid = $result)
vector show element (resn) (id $loopid)
evaluate ($resn = $result)
vector show norm (b) (byresidue(id $loopid) and not hydrogen)
evaluate ($rmsfluc = $result)
```

display \$resn \$resid \$rmsfluc

end loop rms

Script Example III: Solvate in Water

Solvate.inp (download from class web site)

The script

- measures the extent of the structure
- overlays a water box over the structure the necessary number of times
- deletes water molecules too close to protein
- deletes water molecules too far from protein

Geometric and Energetic Analysis

Print Statement

The print statement provides a listing of pertinent information about selected bonds, angles, dihedrals, impropers, and hydrogen bonds. The listing of the print statement can be further reduced by use of the constraints interaction statement (see above).

The following example shows how to print all covalent bonds of residue 40 that deviate by more than 0.1 Å. It also provides information about the rms deviation of the selected bonds:

```
constraints interaction
        ( residue 40 ) ( residue 40 )
end
print threshold=0.1 bonds
```

(for details see online X-PLOR manual, chapter 5)

Geometric and Energetic Analysis

Pick Statement

The pick statement allows one to pick specific energy terms independent of the actual list of bonds, angles, dihedrals, and impropers in the molecular structure.

The following example picks the bond angle value among three arbitrary atoms. Note that the atoms do not have to be bonded to each other, and no parameters are required for this property. Of course, if one tried to pick a different property here, the program would come back with an error message:

```
pick angle
  ( residue 1 and name c )
   ( residue 32 and name n )
   ( residue 5 and name ca )
   geometry
```

(for details see online X-PLOR manual, chapter 5)

Geometric and Energetic Analysis

Advanced Analysis

X-PLOR also provides scripts and tools for:

- Analysis of non-bonded information
- Accessible Surface Area
- Ramachandran plot



Cartesian Coordinates

Coordinate Manipulation and Analysis

The coordinate statement is used to read and manipulate coordinates, such as least-squares fitting to a comparison coordinate set, rotation, translation, and conversion between fractional and orthogonal coordinates.

In the following example, the first set is least-squares fitted to the second (comparison) set using C-alpha atoms only. Note that all atoms are translated and rotated. Then the rms difference between the two sets is computed for backbone atoms and stored in the symbol \$1. Finally, the individual rms differences are printed for all backbone atoms that show rms differences greater than 1Å and the fitted coordinates (C-alpha only) are written to a file.

```
coordinates fit selection=( name ca ) end
coordinates rms selection=( name ca or name n or name c ) end
evaluate ($1=$result)
vector show ( b )
    ( attribute b > 1.0 and ( name ca or name n or name c ))
write coordinates output=outfile.pdb selection =(name ca) end
```

Cartesian Coordinates

Advanced Coordinate Manipulation

X-PLOR also provides scripts and tools for:

- Analysis of rmsd vs. residue number
- Auto-orienting and centering
- Any kind of translating / rotating coordinates
- Computing the radius of gyration
- Distance matrix calculations



$$R_{gyr} = \sqrt{<\left(r_i - < r_i >
ight)^2>}$$

RM SD



(for details see online X-PLOR manual, chapter 6)

Constraints & Restraints: What's the Difference?

- A constraint is a requirement that the system is forced to satisfy
- •With a restrain the system is able to deviate from the desired value

Position Restraints

To a fixed reference position R_i : used during equilibration to avoid dramatic rearrangements of some parts of the system

e.g. position restraints to protein after insertion in bilayer to re-equilibrate the lipids

Distance Restraints

They add a penalty to the potential when the distance between specified pairs of atoms exceeds a threshold value



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Distance Constraints: SHAKE Algorithm



Coordinate Restraints

Advanced Coordinate Manipulation

X-PLOR provides scripts and tools for:

- Point restraints (e.g. attaching atoms to points by a harmonic spring)
- Planarity restraints
- Dihedral Angle Restraints

(for details see online X-PLOR manual, chapter 7)

Coordinate Constraints

Advanced Coordinate Manipulation

X-PLOR provides scripts and tools for:

• Fixing atomic positions

The following example fixes all C-alpha atoms:

coordinates fix=(name ca) end

• Fixing distances between atoms (SHAKE)

(for details see online X-PLOR manual, chapter 8)

Energy Minimization

• Minimization:

Powell's conjugate gradient minimization

- Molecular dynamics: (numerical solution of Newton's equations of motion) with temperature variation (simulated annealing)
- Rigid body dynamics
- Rigid body minimization (with Powell's method)
- Grid search through command language
- Monte Carlo simulated annealing through command language

Powell's Conjugate Gradient Method



- uses gradient information
- a "complete" minimization is a series of one– dimensional minimizations (one for each degree of freedom)

Powell's Conjugate Gradient Method

- started by MINImize POWEll
- Minimization is performed until one convergence criterion is met.
- NSTEp: maximum number of steps
- TOLG radient: target norm of gradient
- Other parameters:
- DROP: expected initial drop in energy (default 0.001, optimal value 10...100)
- NPRInt: Information is printed every NPRINT steps

Notes:

- Minimization defines variables \$ener, \$grad, \$bond... of energy terms that are turned on with FLAG statement
- Minimization often terminates with "Line search abandoned".

A Simple Energy Minimization

To minimize, we need

- \bullet PSF file
- energy parameters
- starting coordinates (X–PLOR PDB format)

structure @@diala.psf end

parameter @@TOPPAR:parallhdg.pro end

coor @@diala.pdb end

mini powell nstep= 50 end

```
REMARK after 50 steps powell write coor output=diala_min.pdb end
```

Example: Building Hydrogens

```
flags exclude vdw elec end  ! For quick hydrogen building
hbuild
    selection = (hydrogen)
    phistep=20
end
flags include vdw elec end
constraints fix = (not(hydrogen))
end
minimize powell
    drop = 20
    nstep = 1000
end
write coordinate output = withhydrogens.pdb end
```

(for details see online X-PLOR manual, chapter 6)

Demo

minimization demo: download from class web site

1. run the following and wait until it exits (this will create the PSF): xplor < prepare.inp > prepare.log &

- 2. read and understand minimize.inp
- 3. run the following: *xplor < minimize.inp*
- 4. become familiar with and understand the output
- 5. you could also do the following to create a log file and look at it as it is being created:

xplor < minimize.inp > minimize.log & ; tail -f minimize.log

6. If you're adventurous the prepare.inp script explains how the PSF is generated:

- first we did not discuss sugars (polysaccharides) in class, you can read more here:

 $http://www.accessexcellence.org/RC/VL/GG/garland_PDFs/Panel_2.03b.pdf$

- we're dealing with sugars and protein here so suger parameters/topolgy files need to be read also
- segments CHA, CHB, CHC, CHD are 4 protein chains with sequence read from start.pdb
- segment CHE contains sugars in linear sequence starting at residue number 5
- an explicit sequence is specified with fake residues 1-4 that are deleted later before reading the coordinates
- then disulfide bond patches (cystein cross-links) are applied to the protein chains
- sugars are highly branched so we need to add also a considerable number of sugar cross-links also
- finally four sugar puckers have to be patched to the alpha from the standard beta form
- hydrogen building
- quick minimization
- writing psf and pdb

7. If you want look at the structures with VMD...

Molecular Dynamics

Newton equations

Molecular dynamics is the numerical solution of Newton's equations of motion

$$m_i \frac{d^2 x_i}{dt^2}(t) = -\nabla_{x_i} E_{TOTAL} \tag{1}$$

- second order differential equation
- masses m_i are defined in topology file
- E_{TOTAL} is the X–PLOR energy function (force field and experimental terms)

The Verlet Algorithm

 \bullet derived from a linear approximation

$$x_i(t+h) = 2x_i(t) - x_i(t-h) + F_i(t)\frac{h^2}{m_i} \qquad (2)$$

• velocities are calculated by

$$v_i(t) = \frac{1}{2h} (x_i(t+h) - x_i(t-h))$$
(3)

- very simple, very stable
- started by

DYNAmics LANGevin ... END DYNAmics VERLet ... END

Example: Newtonian Dynamics

```
! initialize velocities
dynamics verlet
        nstep=1 ! nr. integration steps
        timestep=0.0000001 ! integration step, ps
        iasvel=maxwell ! initial velocity assignment
        first = 300 ! temperature
end
! production run
dynamics verlet
        nstep=1000 ! nr. integration steps
        nprint=10 ! energy values printed every nprint steps
        timestep=0.001 ! integration step, ps
        iasvel=current ! current temperature
        iprfrq=50
                          ! energy statistics printed every iprfrq steps
        ntrfrq=0 ! Frequency of removal of COM motion
end
```

NOTE: Normally one would not initiate temperature directly at 300K but perform slow heating first.

Maxwell-Boltzmann Velocity Distribution

An NVT ensemble simulation at T=300K was terminated and continued as an NVE ensemble simulation. After an equilibration phase, the distribution of velocities from all atoms was determined (red) and fitted to the Maxwell velocity distribution (blue); the best fit corresponded to a temperature T=297.8 K.



Maxwell distribution for kinetic energies

$$f(\epsilon_k) = rac{2}{\sqrt{\pi}} rac{1}{(k_B T)^{rac{3}{2}}} \sqrt{\epsilon_k} \, \exp\left(-rac{\epsilon_k}{k_B T}
ight)$$

Terminology:

NVT: constant number of particles, volume, temperature (temp. coupling)

NVE: constant number of particles, volume, energy (Newtonian dynamics)

Temperature Control I: Velocity Scaling

Prerequisites:

Need to set the following in *dynamics verlet* statement:

ieqfrq =<integer>
frequency of velocity rescaling

first=<real> temperature

iscvel=<integer>
velocity rescale mode (default 0)

The simplest method is periodic explicit rescaling

- calculate actual temperature from velocities
- \bullet rescale with
- if ISCVel=0, overall scaling

$$v_i^{new} = v_i^{old} \sqrt{3nk_B T_o/ < \sum_i m v_i^{old}(t)^2 >} \quad (5)$$

• if ISCVel=1, individual scaling

$$v_i^{new} = v_i^{old} \sqrt{3k_B T_o} / \langle m v_i^{old}(t)^2 \rangle$$
 (6)

• where

n is the number of free atoms in the system k_B is Boltzmann's constant T_o is the target temperature $V_i^{old}(t)$ is the velocity of atom i

Temperature Control II: Langevin Dynamics

• X–PLOR can calculate Langevin dynamics

$$m_i \frac{d^2 x_i}{dt^2}(t) = -grad_{x_i}E + f_i(t) - m_i b_i \frac{dx_i}{dt}(t) \quad (4)$$

- in addition to Newton equation, friction terms:
- f_i is a random force on atom i
- $m_i b_i \frac{dx_i}{dt}(t)$ is a velocity dependent friction term with friction constant b_i
- \bullet the b_i are defined in the FBETA atom property

VECTor DO (FBETA = 10.0) (ALL)

- Langevin dynamics is turned on by choosing RBUF (everything outside RBUF) ILBFRQ > 0
- can be used as temperature control

Example: Langevin Dynamics

! initialize

```
vector do (fbeta=50) (not(hydrogen))
vector do (fbeta=0) (hydrogen)
```

```
dynamics verlet
```

```
iasvel = maxwell
first = 10
nstep = 1
timestep = 0.000001
```

end

```
evaluate ($step = 1) ! stepping variable used, 1ps run
evaluate ($tlan = 10) ! temperature variable used
```

Example: Langevin Dynamics

```
while ($step < 31) loop main ! 30 ps heating to 300K
  dynamics langevin
        ntrfrq = 100
        nstep = 1000
        ilbfrq = 1000
        timestep = 0.001
        iasvel = current
        iprfrq = 50
        nprint = 10
        tbath = $tlan
        rbuf = 0
  end
  ! write coordinates every ps
  evaluate ($outfile = "langevin_"+ encode($step) + ".pdb")
  write coordinates
        output = $outfile
  end
  evaluate ($step = $step + 1)
  evaluate ($tlan = $tlan + 10)
end loop main
```

Temperature Control III: Berendsen Coupling

• Berendsen's method: Langevin dynamics with adjustable friction coefficient and zero random force

$$b_i = b_i^I (T_o/T - 1)$$
 (7)

- if $T > T_o, b_i$ is positive (cooling)
- if $T < T_o, b_i$ is negative (heating)
- switch on by

```
vector do (fbeta = 10) (not hydro)
dynamics verlet
   ...
   TCOUpling = TRUE
   ...
end
```

Temperature Control III: Berendsen Coupling

Some important parameters:

- TCOUPling : switch on Berendsen's method
- TBATh : target temperature for Langevin and Tcoupling
- FIRSttemp : initial temperature
- IASVelocity : initial velocity distribution
- NPRInt : output frequency
- \bullet NSTEp : number of steps
- \bullet TIME step : intergration step
- NTRFrq : removal of COM motion
Example: Slow Berendsen Cooling

```
evaluate ($bath = 1000)
while ($bath > 50) loop cool
  evaluate ($bath = $bath - $tempstep)
```

dynamics verlet assumes initial velocities have been set velocities have been set dynamics verlet nstep=1000 time=0.005 iasvel=current tcoup=true tbath=\$bath nprint=\$nstep iprfrq=0 ntrfrq=9999 end

end loop cool

Resources and Further Reading

WWW:

http://xplor.csb.yale.edu

Books:

Chapters 1-11 in: A.T. Brunger, X-PLOR Version 3.1 (Yale U Press, 1992) online free at http://alpha2.bmc.uu.se/local_html/xplor_mirror.html

Acknowledgement:

Michael Nilges Primer http://www.pasteur.fr/recherche/unites/Binfs/xplor/primer/ Lectures 2-4